

A person-rooted spatial analysis of demonstratives

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Person- *vs* distance-oriented demonstrative systems

Exophoric demonstrative systems (**Anderson & Keenan 1985**):

- **person-oriented** demonstrative systems

- locate a referent w.r.t. one of the speech act participants
- Japanese:

kore	sore	are
this (near speaker)	that (near hearer)	that (far from both)

- **distance-oriented** demonstrative systems

- locate a referent at different distance degrees w.r.t. the speaker
- Scots:

this	that	yon(der)
this (proximal)	that (medial)	that (distal)

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Today: unified analysis combining person and distance.

Proposal / 1

- Claim: Demonstrative systems are **person-oriented**.

Evidence:

1. degrees of distance from the hearer;
2. role of hearer in distance-oriented systems;
3. interactions & inconsistencies.

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- **Distance** distinctions: **extensions** of the person core – cf. **Lander & Haegeman 2018**, but:

1. **Person features**, rather than locative ones.

New empirical arguments:

- four-way (person) deictic oppositions;
 - encoding of further indexical information.
- Person system: see **Harbour 2016**.

2. Derivation

Proposal / 2

- Informal semantics of demonstratives: express a **spatial relation to person** – cf. **spatial prepositions** (Svenonius 2010, *i.a.*).

xPP [$_{Deg\mu}P$ [$_{Meas}P$ 1m] \emptyset [$_{Loc}P$ in [$_{AxPart}P$ front [$_{KP}$ of [$_{DP}$ the tree]]]]]]

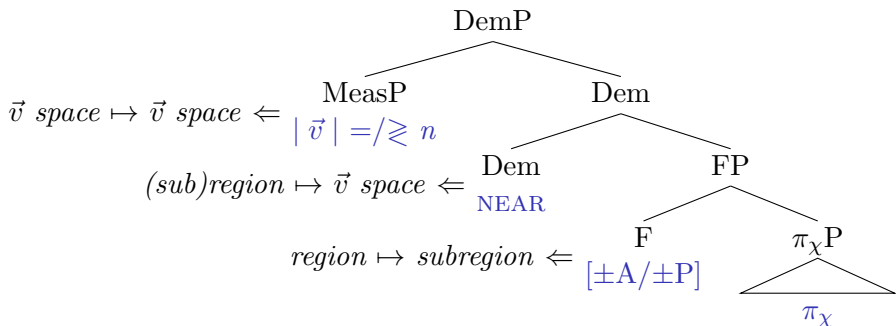
DemP [$_{Dem}P$ [$_{Meas}P$ (VERY)] NEAR [$_{FP}$ $\pm A/\pm P$ [$_{\chi}P$ SPACE OF [$_{\pi}P$ π]]]]]

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Thank you!

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